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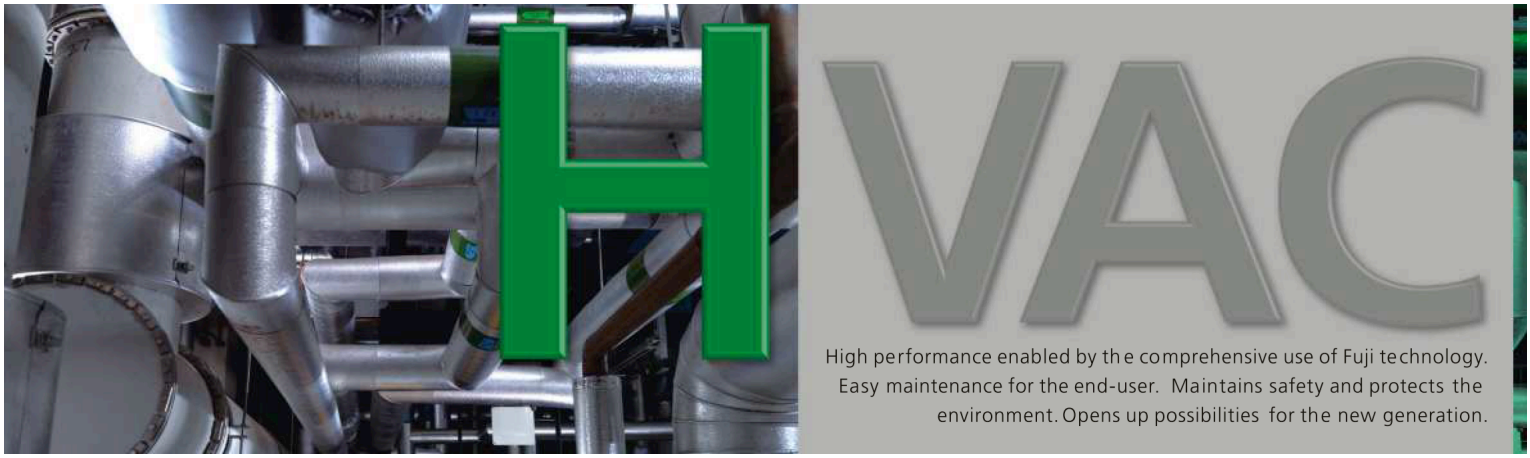

QUICK GUIDE
SINGLE PUMP CONTROL

FRENIC-HVAC

Frequency inverter for pump control applications

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Version	Details	Date	Written	Checked	Approved
1.0.0	Draft version	03/10/13	J. Alonso		
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Thank you for purchasing FRENIC-HVAC, Fuji Electric's inverter for pump and compressor applications. This guide is structured as follows:

Chapter 0
Introduction to pressure control systems

The target of a pressure control system is to provide a variable flow with a constant pressure for the water system of an apartment building, machine refrigeration systems, mixing liquids in chemical industry, etc.

A very typical example is to provide the water supply for a residential building. In this case, the flow (water consumption) is greater in the morning than during the night (when it is almost zero). The pressure control system must be able to provide, at the same pressure, both types of consumption (daytime→higher flow, during the night→ almost no flow); in addition, the system has to adapt to the demand variations that occur normally in this kind of application, for example, when people turn on and off many taps at the same time.

The *FRENIC-HVAC* inverter has been designed to fulfil all the requirements of a single pump control system. Some of its more important functions are:

- Stop function due to low water flow (Sleep Function)
- Start-up function because of water demand (Wake-up Function)
- Operation limits (current, voltage and frequency) to protect the motor and the pump
- Possibility to add an additional pump (FDT Function) to single pump control
- Many functions to avoid overpressure and water losses (Warnings, alarms, etc.)
- Pressure sensor disconnection detection
- Selecting different warnings (low-pressure, overpressure, etc.)
- Protective function to protect pump from the absence of water (Dry well function)
- “By-pass” sequence integrated
- Control of the delay time between connection and disconnection of the contactors
- Display units and sensor range adjustments
- Multiple frequency command selection (by means of digital inputs)
- Dew condensation prevention Function
- Energy Saving Functions
- Anti-jam Function

Regulation by means of PID control:

A PID control is a regulation system involving the set value (SV - desired pressure) and a process value (PV - Feedback, measure of real pressure or flow from a transducer). From these two values the difference, or error, is calculated, subtracting one from the other. The PID control then adjusts its output demand (MV - pump’s speed) in order to minimize the error:
-If the error is positive (desired pressure greater than real pressure) speed should increase
-If the error is negative (desired pressure lower than the real pressure) speed should decrease
-If the error is zero (desired pressure equal to real pressure) speed should stay at the same level

Parameters (gains) to adjust: Proportional, Integral and Derivative components (though Derivative component is not normally used in this application) help to select how quickly the system will respond to pressure and consumption changes. Normally, a quick (dynamic) response is desired, but pressure peaks and oscillations must be avoided.

Chapter 1
Single pump control

When a regulated pump is being controlled, it's necessary to consider certain parameters in order to allow the inverter to control the pump's start-up and stop, controlling speed to maintain the desired pressure, etc.

The schematic to implement control by only 1 pump by means of FRENIC-HVAC inverter, is as follows:

Please note the pressure transducer is connected to the inverter's analog input C1 (4-20 mA)

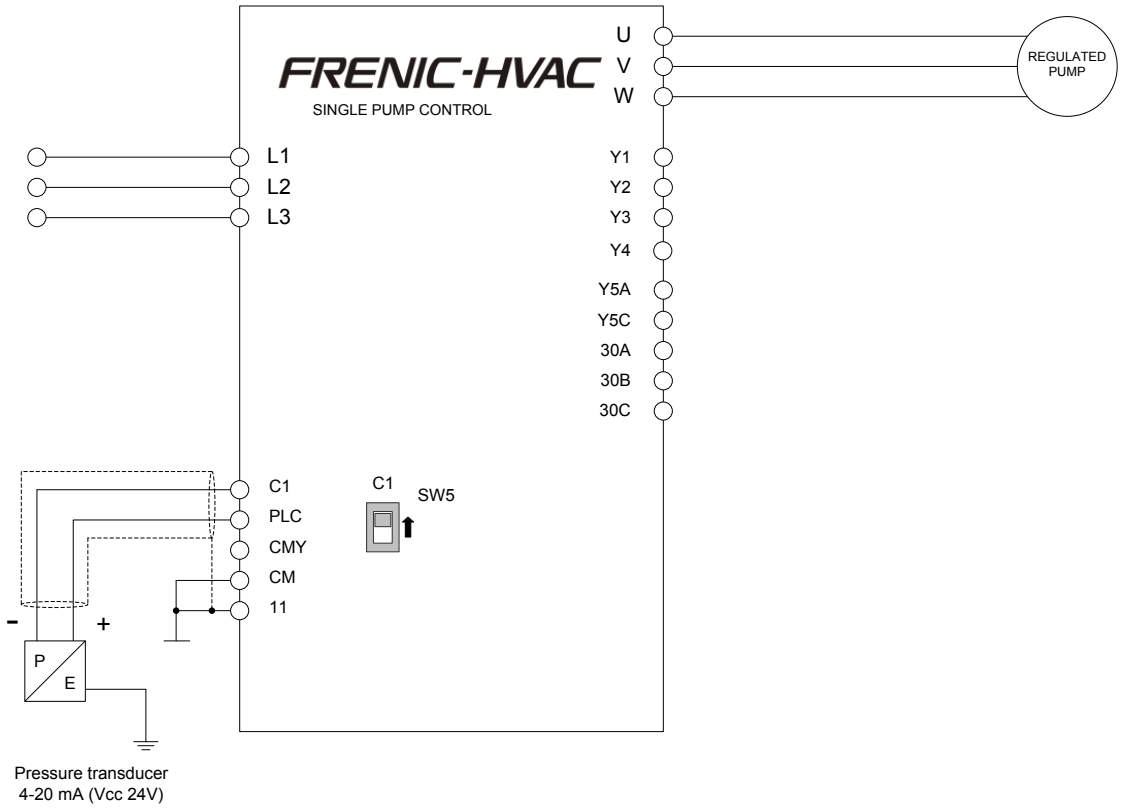

Figure 1.1: control schematic for a single pump

By means of the TP-A1 keypad, a digital input or an analog set point, the desired pressure can be selected. Once this pressure is set, inverter will modify pump's speed between a minimum (J119 = F16 (Hz)) and a maximum (J118=F15=F03 (Hz)) frequencies, in order to stabilize the pressure.

To work in this way, the integrated PID Control 1 must be enabled (J101) and adjusted properly. Then, the inverter's response should be the required action to control the application.
PID's response can be modified by means of parameters J110 and J111 (Proportional gain and Integral time).

When the "RUN" signal is switched on (either FWD or REV), the inverter will increase the output frequency (always after the period time defined in J454 (s)). In order to control this rising output, some parameters are available: F23 (Hz) controls the starting frequency, F16 the frequency limiter (low) and the ramp from one to the other (F07) (s). PID Control 1 is enabled since RUN command is given. In the same way, when the "RUN" signal is switched off, the inverter decrease its output frequency to the level defined in F25 (Hz) (the deceleration time is set in F08 (s)), and stops the PID Control 1.

Sleep Function *(related parameters: J150 (Hz), J151 (s))*

Sleep function can be useful to stop one pump when the speed is below a rate where there is no flow (pump doesn't impel).

Once the demand frequency level below this rate (the frequency when the pump begins to move the water but not enough to create a flow) is known, parameter J150 (Hz) should be set slightly higher than this frequency.

Through this function, is possible to avoid possible mechanical problems that could (over time) damage pump components or 'boil' the water with the wasted energy causing excess pressure and leaks. In addition, stopping the pump when it's not really needed means, obviously, Energy Saving.

So, Sleep Function will be applied if the inverter's demand output frequency is lower than the 'sleep' level stored in parameter J150 (Hz) and it stays at a lower level for a time longer than that specified in J151 (s).

In Figure 1.2 and 1.3 sleep function is shown. The deceleration time to get to the "Stop Frequency" is stored in F08 (s).

In order to have this function active, J149 must be different than 0. For additional details, refer to J149 parameter description.

Important: Sleep frequency (J150 (Hz)) must be lower than the wake-up frequency (J157 (Hz)) and must be higher than the minimum frequency (F16=J119).

Wake-up function *(related parameters J157 (Hz), J158, J159 (s))*

Wake-up function is useful to start-up a pump again that previously was stopped by the sleep function.

In order to wake up a pump two condition must be accomplished:

MV ≥ J157 (Hz)		**|SV – PV|≥ J158 (*)**		**Delay Time ≥ J159 (s)**
Manipulated value (MV, PID's output) must be greater than the level stored in J157 (the current MV value is shown on TP-A1 according to recommended setting)	and...	The absolute value of the process error (the subtraction between the process value and the set point value) must be greater than the percentage in J158	and...	The percentage set in J158 is kept or MV is above J157 level longer than the time specified in J159

(*) J158 units depend on J105. Default setting is J158 units depend on PID Feedback 1 units (either C58, C64 or C70, depending on the analogue input used as a feedback)

As one or two conditions have to be met in order for the pump to start, multiple start-ups due to pipe losses can be avoided. So, we avoid waking up the pump unnecessarily or too often.

Figure 1.2 and 1.3 show how the pump goes to sleep mode and wakes up depending on J149 setting.

In addition, sleep frequency must be higher than minimum frequency (F16=J119)

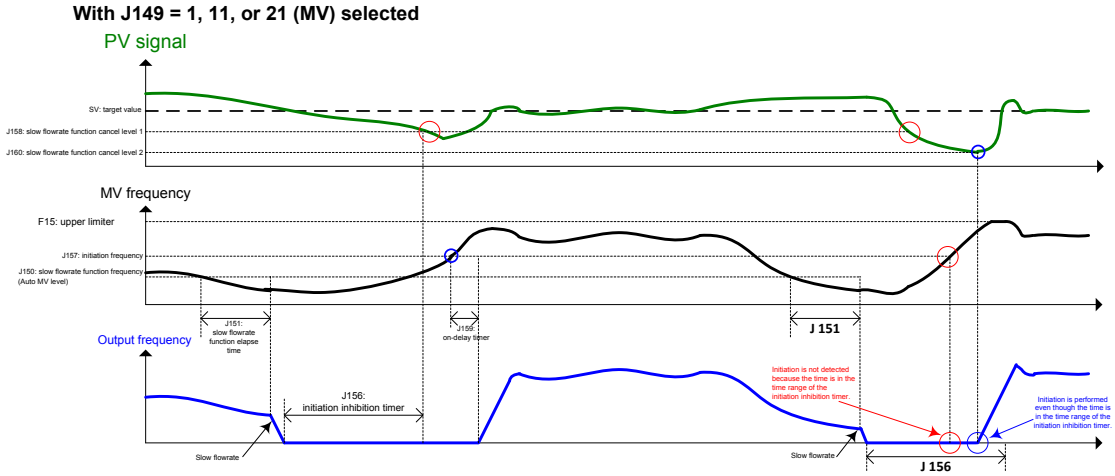

Figure 1.2: Speed control behaviour while sleep and wake-up functions are enabled and J14=1,11 or 21.

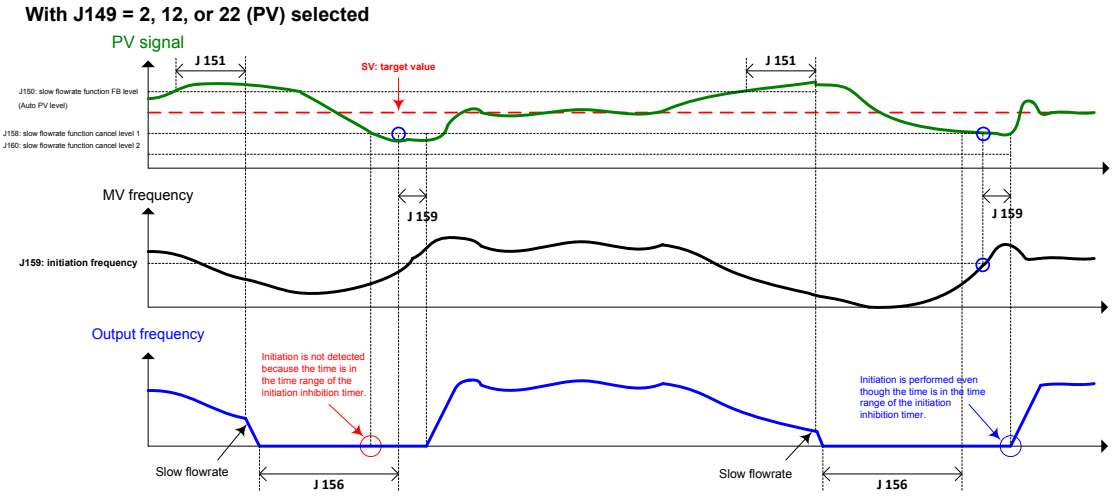

Figure 1.3: Speed control behaviour while sleep and wake-up functions are enabled and J14=2, 12 or 22.

Function codes set-up

The following table (table 1.1), called “Common parameters to the all pump control systems”, shows the common parameters to all pump control systems using *FRENIC-HVAC*, these are known as the basic parameters.

In other chapters, Specific Parameters’ table will be shown. These parameters will depend on the chosen control system.

Note: The following values are shown as an example and could not work properly in your application.

Table 1.1: Common parameters to all pump control systems

	Single pump control parameters basic setting			FRENIC-HVAC
	Name	Default setting	Example’s Value	**User’s Value**
H03[*1]	Data initialization	0	**73: Single pump**	
F02	Run command	0	**1**	
F07	Acceleration Time 1	20.00 s	**3.00 s**	
F08	Deceleration Time 1	20.00 s	**3.00 s**	
F11	Electronic Thermal Overload protection. Overload detection Level	100% of the motor rated current	**13.0 A**	
F12	Electronic Thermal Overload protection. Time constant	5.0 min (22kW or below) / 10.0 min (30kW or above)	**5 min**	
F15	Frequency Limiter. High	70.0 Hz	**50.0 Hz**	
F16	Frequency Limiter. Low	0.0 Hz	**25.0 Hz**	
E62	Terminal [C1] extended function	0	**5**	
C64	Analog input adjustment for terminal [C1]. Display unit	2: %	**44: bar**	
C65	Analog input adjustment for terminal [C1] (max. scale)	+ 100.00	**+10.00 (Transducer’s pressure)**	
K10	Main monitor display item selection	0: Speed monitor	**51: PV**	
K16	Sub monitor 1 display item selection	13: Output current	**50: SV**	
K17	Sub monitor 2 display item selection	19: Input power	**1: Fout1**	
P01	Motor. Number of Poles	4	**4**	
P02	Motor. Rated capacity	Rated Capacity Standard Motor	**5.5 kW**	
P03	Motor. Rated current	Rated Current Standard Motor	**13.0 A**	
H91	Current input wire break detection	0.0 s	**0.5 s**	
J101	PID Control 1. Mode Selection	0	**1**	
J110	PID Control 1. Gain P	0.100	**2.500**	
J111	PID Control 1. Integral time	0.0 s	**0.2 s**	
J118	PID Control 1. Upper limit of PID process output	Inherit	Inherit	
J119	PID Control 1. Lower limit of PID process output	Inherit	Inherit	
J149	Slow flow rate stop function. Mode selection	0	**1: Manual operation (stop judgement MV)**	
J150	Slow flow rate stop function. Sleep frequency	Auto	**35.0 Hz**	
J151	Slow flow rate stop stop function. Sleep frequency level latency	0 s	**15 s**	
J157	Slow flow rate stop function. Wake-up frequency	0 Hz	**38.0 Hz**	
J158	Slow flow rate stop function. Cancel deviation level 1	OFF	**0,5 bar**	
J159	Slow flow rate stop function. Cancel delay timer	0 s	**1 s**	

*[*1] Setting H03=73 a macro with a default setting for HVAC Single pump application will be used. It means that most of the recommended values of this guide will be automatically programed.*

CONDITIONS TO ACHIEVE GOOD CONTROL WITH A SINGLE PUMP

If it’s necessary to use a different parameter set-up to that shown in the above “Example Values” column, please bear in mind the following conditions:

Sleeping/ Wake-up frequency Conditions

F03 = F15 = J118 > J157 > J150 > F16 = J119

Maximum frequency | Frequency to wake-up | Frequency to sleep | Minimum frequency

SINGLE PUMP CONTROL PARAMETERS DESCRIPTION

Basic Function

- F02: Run Command

This function code defines the way in what the “RUN” signal will be given to the inverter in order to start the pressure control.

Usually, “RUN Command” is sent to the inverter by means of the digital input (F02 = 1). That is, switching on FWD or REV (control terminals in the inverter) digital inputs enables the inverter output.

A RUN command can be also activated by means of the TP-A1 keypad, pushing FWD or REV buttons.

- F07: Acceleration Time 1
- F08: Deceleration Time 1

These acceleration/deceleration ramps are used in two cases:

1. After the RUN Command is ON, F07 ramp is used to achieve the frequency in F16 or J119 (the biggest one of both values).
   When the RUN Command is switched OFF, F08 value defines the deceleration ramp to go from the current frequency to the stop frequency (F25).
   At every change of output frequency, even due to the PID output change.

2. These ramps are also used when the inverter is connected/disconnected from the commercial power supply if function codes J455 and J458 are set to 0.00 (please refer to the corresponding diagrams in the following chapters).

- F11: Electronic Thermal Overload Protection. Overload detection level
- F12: Electronic Thermal Overload Protection. Thermal time constant

By means of these two parameters is possible to adjust the overload protection function. Normally, F11 will be adjusted to the motor’s rated current and F12 to 5 minutes.

- F15: Frequency Limiter. High
- F16: Frequency Limiter. Low

These two parameters define the frequency limits, and the inverter will never go outside of these limits during pump control.

It’s normal to adjust the parameters F15, J118 and F03 with the same value.
Equally, F16 should be equal to J119, too.

Inputs Set-up

- E62: Terminal [C1] extended function

This parameter can be used to select the function for analog input C1.

Usually this parameter is set to E62 = 5, this setting will define the [C1] analog input as PID Feedback (pressure transducer).

Motor Map

- P01: Motor. Number of poles
- P02: Motor. Rated Capacity
- P03: Motor. Rated Current

In these parameters must be stored the number of poles, rated capacity and rated current as are shown in the motor’s nameplate.

Special Functions

- H91: Current input wire break detection

Disconnection of pressure sensor (cable failure).

When a value is stored in parameter H91 (between 0.1 and 60.0 seconds) the inverter will generate an alarm (**CoF**) when it notices that C1 signal current is missing (C1 current < 2mA) during a time longer than the value in H91.

H91 = OFF → function disabled.
H91 ≠ 0 → function enabled.

PID and pump control

- J101: PID control 1. Mode selection

When J101 = 1 and the error between Set Point and Process Value is positive (SP - PV > 0), the PID controller makes a positive output action control (increasing MV). Alternatively when the error between Set Point and Process Value is negative (SP - PV < 0), the PID controller makes a negative output action control (decreasing MV).

Alternatively, if J101 = 2 and the error between Set Point and Process Value is negative (SP – PV < 0) the PID controller makes a positive output action control (increasing MV). Alternatively when the error between Set Point and Process Value is positive (SP - PV > 0), the PID controller makes a negative output action control (decreasing MV).

- J110: PID Control 1. P Gain

This parameter is used to set the PID controller's proportional gain (P). This parameter must be adjusted because its value depends on the application.

A high P value produces a PID controller's quick response. Otherwise, a low P-value produces a slow response.

- J111: PID Control 1. Integral Time

This parameter is used to adjust PID's integral time (I). This parameter must be adjusted because its value depends on the application.

A high integral time value produces a PID slow response. Otherwise, a low I value produces a quicker response.

- J118: PID control 1. Upper limit of PID process output
- J119: PID control 1. Lower limit of PID process output

These parameters specify upper and lower limit process output values.
We set J118 = F15 = F03 and J119 = F16.

PID Control 2 is also available. Each function explained for PID Control 1 has an equivalent function in PID Control 2. For additional information, refer to FRENIC-HVAC User Manual.

Chapter 2
Single pump control + 1 additional pump

The schematic to implement a single pump control with 1 regulated pump + 1 additional pump with FRENIC-HVAC inverter is shown in figure 2.1. Please, pay attention on the pressure transducer's wiring, connected to the inverter's analog input C1 (4 – 20 mA).

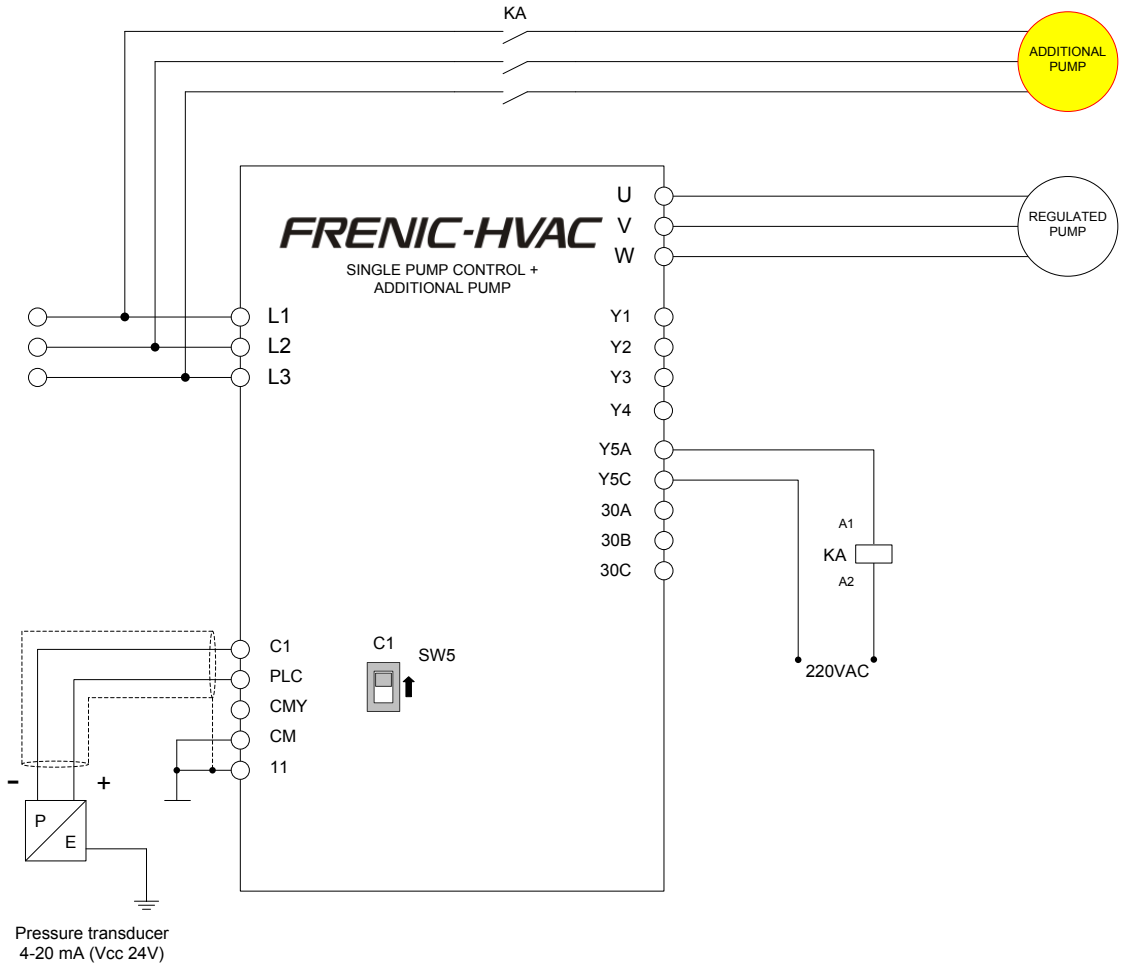

Figure 2.1: Schematic for single pump control with 1 regulated pump + 1 additional pump

This control system consists on a regulated pump controlled exclusively by the inverter and one additional pump working in "ON-OFF control" mode connected directly to the commercial power supply. The inverter will connect/disconnect the additional pump to the commercial power supply in order to achieve the desired pressure.

The additional pump will be connected to the commercial power supply when the inverter output frequency is higher than the value stored in E31 (Hz).

The additional pump will be disconnected from the commercial power supply when the inverter output frequency is lower than E31 – E32 (Hz).

Using this control, the *FRENIC-HVAC* inverter is able to control up to 2 pumps.

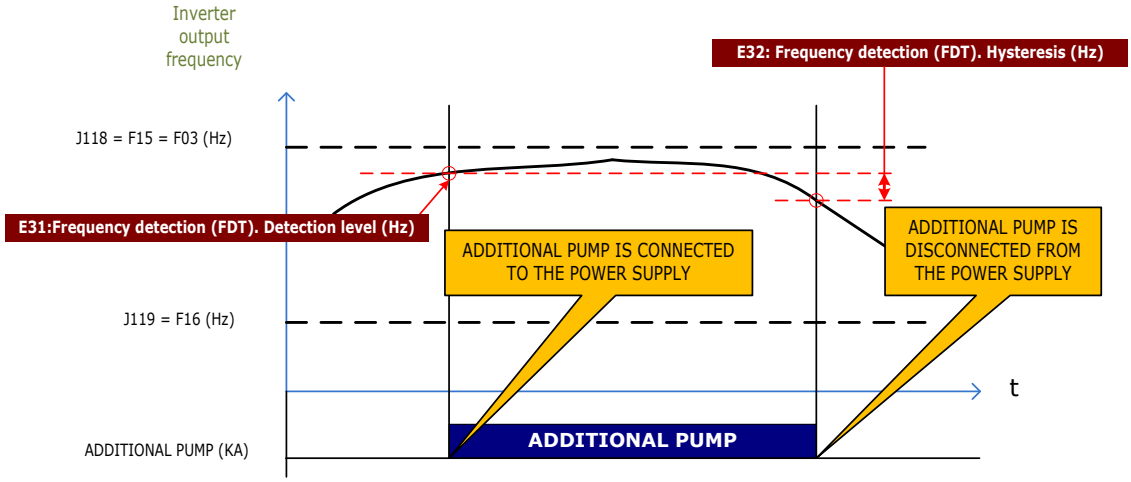

Figure 2.2: Additional pump's connection/disconnection time diagram

Set-up with 1 regulated pump + 1 additional pump

Table 2.1 shows the specific function codes to control a single pump control + 1 additional pump.

Table 2.1: Specific function codes for single pump control + 1 additional pump system

	Specific Function Codes for mono-regulated pump control with 1 regulated pump + 1 additional pump			
	Name	Default Setting	Example's value	**User's value**
E24	Status Signal Assignment to Y5A/C	15	**2 (FDT)**	
E31	Frequency Detection (FDT). Level	50.0 Hz	**47.0 Hz**	
E32	Frequency Detection (FDT). Hysteresis	1.0 Hz	**8.0 Hz**	

Please consider that, in order to set up correctly the inverter-driven pump, we should use additionally the parameters described in table 1.1.

CONDITIONS TO ACHIEVE GOOD CONTROL WITH A MONO-REGULATED PUMP CONTROL + 1 ADDITIONAL PUMP

If setting function codes' values different from the "Example's Value" column, it is recommended to keep in mind the following restrictions:

Conditions for Sleep/Wake-up frequency

F03 = F15 = J118 > J157 > J150 > F16 = J119

Maximum frequency | Frequency to wake-up | Frequency to sleep | Minimum frequency

Conditions for the connection of the additional pump

F03 = F15=J118 > E31 > E31-E32 > J150 > F16 = J119

Maximum frequency | Frequency to connect additional | Frequency disconnection additional | Frequency to sleep | Minimum frequency

PARAMETERS DESCRIPTION

Outputs Set-up

- E24: Status Signal Assignment to Y5A/C

The function code E24 defines the signal assigned to digital output Y5A/C.

In order to implement a mono-regulated pump control system with an additional pump, the Y5A/C terminal's signal must be set to 2, corresponding to FDT function.
This digital output should be connected to relay RA (see connection diagram in figure 2.1).
By means of FDT function it is possible to activate the digital output Y5A/C when the regulated pump's output frequency raises above the frequency level defined in the function code E31.
Using function code E32 it is possible to define a hysteresis, in order to avoid that the signal Y5A/C is switching ON/OFF continuously.

- E31: Frequency Detection (FDT). Level

By means of this function code, it is possible to set the frequency level upon which the FDT signal (function "2") will be activated. Normally, the level set in E31 should be slightly smaller than the value in F03=F15.

In this way, the additional pump will be switched-on when regulated pump is almost at maximum speed.

- E32: Frequency Detection (FDT). Hysteresis

With this parameter it is possible to adjust the hysteresis level for the deactivation of the FDT digital output. The value of E31-E32 must be slightly bigger than the data in J150 (frequency to sleep).

With this setting, it's possible to disconnect the additional pump before being close to the sleeping frequency.

Chapter 3
Additional Functions

Dry pump function (Related function codes -> E80, E81)

Target: to make the inverter enter a STOP state, displaying an error code, when motor torque decreases below a set level for a specified period of time.

- Digital Inputs to use: X5 (with “Enable External alarm Trip” command assigned to it)
- Digital Outputs to use: Y1 (with “Low Output Torque Detected” signal assigned to it)
- Wiring:

  - Connect X5 to Y1
  - Connect CMY to PLC (*)

- Set-up:

  E05 (X5) = *1009: Enable external alarm trip (THR)*
  E20 (Y1) = *45: Low output torque detected (U-TL)*
  E80 = *Detect Low Torque. Level (%)*
  E81 = *Detect Low Torque. Timer (s)*

Error Message: when the output torque drops below the level set in E80 for the time in E81, the inverter output will be switched off, and the inverter will display the *OH2* error code. This error can be reset by means of the keypad or by means of a digital input (*8: “Reset Alarm” (RST)*).

(*) Assuming that the logic of the digital inputs is Active-High Logic (the common of the inputs is PLC (+24VDC) and inputs’ logic switch is in SOURCE).
If the common of the inputs is terminal CM (0 VDC) (Active-Low Logic in the inputs), please connect together terminals CMY and CM and set the logic switch to the SINK position.

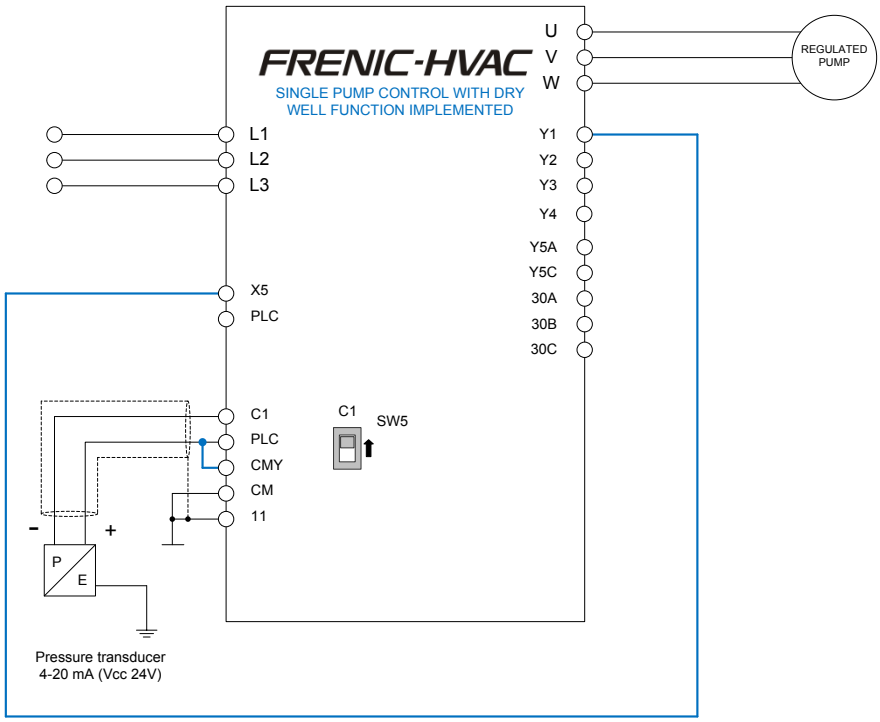

Figure 3.1: Pump control schematic for Dry well function

Overpressure alarm (related function codes -> J127, J128, J129, J130 and J131)

Target: make the inverter enter a STOP state and display an error code, when the process value (Feedback – pressure transducer) rises above a predefined level.

- Set-up:

  J127 = *1: Enable (Free run stop (PV1 trip)).*
  J129 = *PID Control 1. Feedback Failure Upper Limit (%)*
  J130 = *PID Control 1. Feedback Failure Lower Limit (%)*
  J131 = *Feedback failure detection time (s)*

Error Message: when the process value (Feedback value, Pressure transducer) is above the value set in J129 (upper limit) or below the value set in J130 (lower limit) during the time in J131 (Feedback failure detection time), the inverter's output is switched off and the inverter will display *PV1* error code. This error can be reset by means of the TP-A1 keypad or by means of a digital input (*8: "Reset Alarm" (RST)*).

Note: In order to select other alarm modes, please see description of function code J127 (PID Control 1-Feedback failure detection-Mode Selection) in the User Manual of the FRENIC-HVAC inverter.

PID Display units set-up (related function codes -> C64, C65, C66)

In order to display the values of PID control (SV, PV, MV, etc.) in engineering units, it is needed the adjustment of the value in C65 according to the sensor range.

Therefore the user will be able to enter the Command (set point) Value in user units (C58, C64 or C70), instead of percentage (of PID range).

For example, if the transducer used has a 4-20 mA output signal range, where 20 mA correspond to 160 bars, the function code C65 must be set to 160 and C64 to 44 (Units displayed in [C1] to bar).

If the transducer used has a 4-20 mA output signal range, where 20 mA correspond to 10 bars, the function code C65 must be set to 10 and C64 to 44.

The feedback value, in bars and the process command value can be seen in Menu 6: PID Monitor. Those parameters can be also displayed on keypad main screen. For additional information check k parameters.

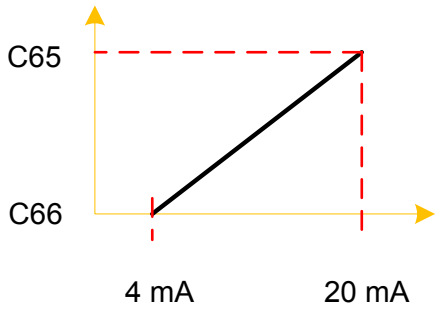

Figure 3.2: PID Display coefficients

The modification of C64 will modify also the units and the meaning of the following parameters:

Table 3.1: Parameters affected by C64 setting

Parameter	Description
C65	Analogue input adjustment for Terminal [C1] (Maximum Scale)
C66	Analogue input adjustment for Terminal [C1] (Minimum Scale)
J106*1	PID control 1 (Maximum Scale)
J107*1	PID control 1 (Minimum Scale)
J114*1	PID control 1 (Anti-reset wind-up)
J122*1	PID control 1 (Upper level alarm (AH))
J124*1	PID control 1 (Lower level alarm (AL))
J129*1	PID control 1 (Feedback failure upper-limit)
J130*1	PID control 1 (Feedback failure lower-limit)
J147*1	PID control 1 (Cancel PV level)
J158*1	PID control 1 (Cancel deviation level 1)
J160*1	PID control 1 (Cancel deviation level 2)
J178*1	Dry Pump Protection (Deviation)
J184*1	End of Curve Protection (Deviation)
J191*1	Filter Clogging Prevention Function (Load resistance PV signal)
J467*1	Auxiliary Motor (PV operation level)

*1: If [C1] analogue input signal is selected as a PID feedback (E62 = 5) and J105 = 0: Inherit. If [C1] signal is used in PID 2, or an external PID, some J2xx, J5xx or J6xx functions may be modified also.

➢ *Multiple PID set point selection*

Using digital inputs, it is possible to select between four PID set point values.

To perform the multiple selection, functions "*171: PID-SS1* " and "*172: PID-SS2* " must be assigned to two digitals inputs among X1, X2, X3, X4,X5,X6 or X7 (E01-E07).

The selected Set Value depends of the combination of these two inputs, as shown in the table below:

Table 3.2: Multiple PID set-point selection

PID-SS2	PID-SS1	PID set point selection
0	0	Depends on J102 setting
0	1	J136
1	0	J137
1	1	J138

➢ *Dew condensation prevention function (related function codes -> F21, F22, J21)*

By means of a DC current injection, it's possible to keep the motor warm to prevent condensation. Please note a digital input should be activated to enable this function (for instance X4, by using function code E04).

Example

E04 = *39: Protect motor from dew condensation (DWP)*
F21 = 10 %
F22 = 1 s (T ON)
J21 = 1 % (DUTY CYCLE)

With this adjustment, there will be a DC current injection every 100 seconds, equivalent to the 10% of the rated current, during 1 second.

$$J21(\%) = \frac{F22}{T} \times 100$$ In this example: $$T = \frac{F22}{J21} \times 100 = \frac{1}{1} \times 100 = 100s;$$

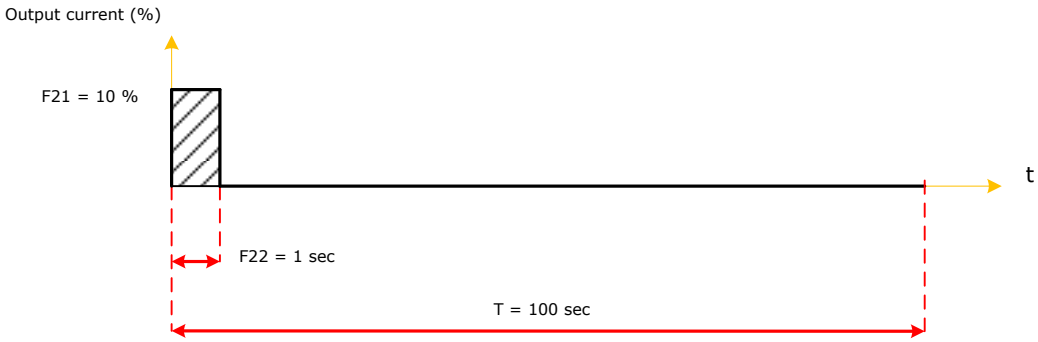

Figure 3.3: Output current when Dew Condensation prevention function is enabled

PID Integral component hold

1. Holding PID integral component while pump is in sleep mode

Target: Make the inverter maintain (hold) the PID controller integral component once the regulated pump has gone to sleep.
The main purpose is to avoid overshooting when the pump wakes up.

Applicable when: The installation has a lot of leakage.

Explanation: The pump provides pressure to the installation, and when the pressure command level is reached, if there is no consumption, the inverter will bring the pump to sleep.
Due to the leakages/losses, the pressure will decrease and the inverter will start up the pump again in order to reach the set point value. This cycle can be repeated until real flow consumption appears.

In old installations, this sleep/wake-up cycle could be repeated continuously.

If you want to make this repetition slower (to make longer the time between sleep and wake-up), the functions codes J158 and J159 can be useful (two additional conditions to wake up the regulated pump are added).
Normally, by using these function codes, it is possible to separate the sleep and wake-up events. The idea is to increase J158 (% of error) for making the time between sleep and wake-up long enough.

But, what happens if the value in J158 is too high?

…of course, the pump's wake-up will be delayed enough, but the accumulated process error will cause a bigger integral action, producing a pressure overshoot when the regulated pump wakes up.
The pressure overshoot varies depending on each application, and it can be higher than expected. In addition, it depends also on the values in J158 and J159 and PID gains (J110, J111 and J112).
In order to avoid the overshoot, holding the integral while the pumps sleep can be useful (avoiding the error integration)

- Digital Inputs: X4 (set to hold integral action function)
- Digital Outputs: Y2 (set to "Motor stopping due to slow flow rate under PID control" function)
- Wiring:

  - Bridge X4 and Y2
  - Bridge CMY and PLC (*)

- Set-up:

  E04 (X4) = *34: Hold PID integral component (PID-HLD)*
  E21 (Y2) = *44: Motor stopping due to slow flowrate under PID control (PID-STP)*
  J158 = 20% (value recommended but adjustable)

(*) Assuming that the logic of the digital inputs is Active-High Logic (the common of the inputs is PLC (+24VDC) and inputs' logic switch is in SOURCE).
If the common of the inputs is terminal CM (0 VDC) (Active-Low Logic in the inputs), please connect the terminals CMY and CM and set the switch to the SINK position.

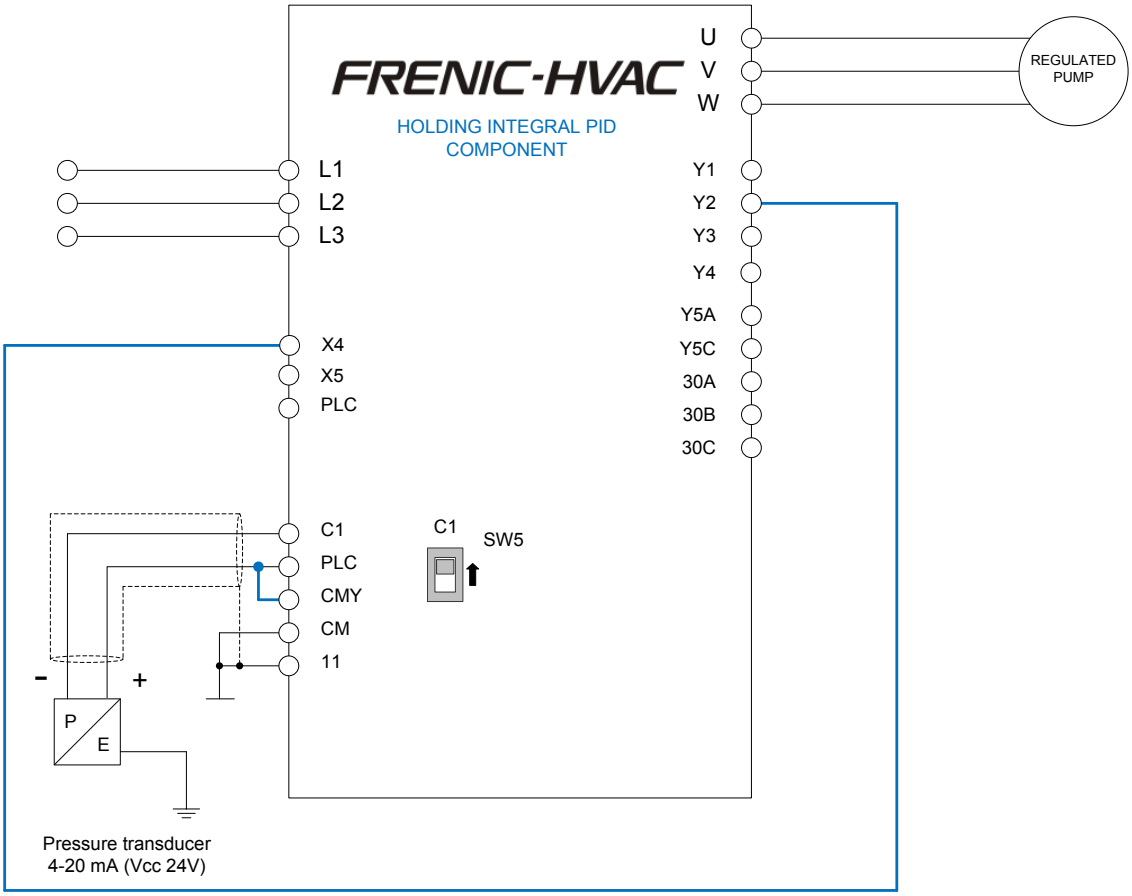

Figure 3.4: Pump control schematic for holding PID Integral component when pump is in sleep mode

2. Holding integral PID component during the process (anti-reset wind-up)

J114 function code can be used to hold the integral PID component.

The integral component will be active only when the difference (error) between process value (PV) and set point (SV) is inside the limits defined by J114 function code. If bigger than these limits, current integral PID component will be held.

Data setting range: OFF (Function disabled), 0.01 to 9990.00 (setting range is limited by the maximum and minimum scales). Units depend on C44 setting.

Example:

For instance, if the transducer installed is 10 bar (C65 = 10) and J114 is set at 1 bar (C64=44: bar), integral PID component will be active when the error of the system (error = SV-PV) is less than 1 bar. On the other hand, for errors larger than 1 bar integral PID component will be held at its current value.

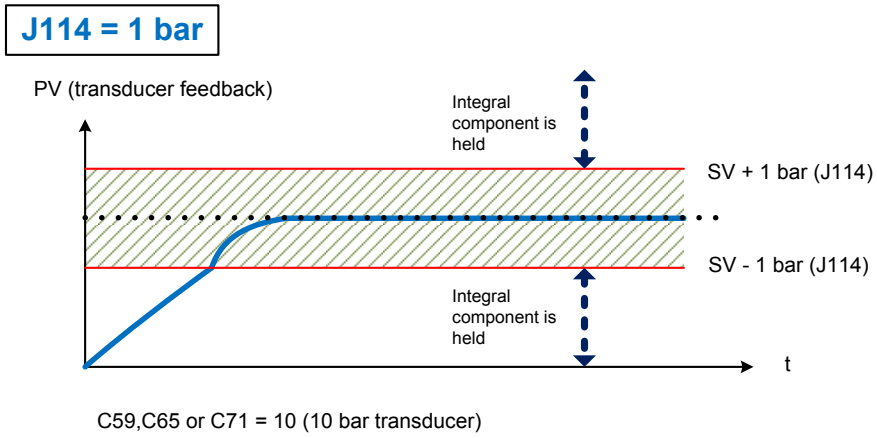

Figure 6.4: PID behaviour when function J114 is used.

Chapter 4
Complete Function Codes' List v. W1S11600

*Only function codes' related with this Pump Control Quick Guide are shown. For more details about other functions, please check User Manual.

F codes: Fundamental Functions

Code	Name	Data setting range	Change when running	Data copying	Default setting	
F00	Data Protection	0: Disable both data protection and digital reference protection 1: Enable data protection and disable digital reference protection 2: Disable data protection and enable digital reference protection 3: Enable both data protection and digital reference protection	Y	Y	0	
F01	Frequency Command 1	0: ⏶ / ⏷ / ⏴ / ⏵ keys on keypad 1: Voltage input to terminal [12] (-10 to +10 VDC) 2: Current input to terminal [C1] (4 to 20 mA DC) 3: Sum of voltage and current inputs to terminals [12] and [C1] 5: Voltage input to terminal [V2] (0 to 10 VDC) 7: Terminal command ***UP/DOWN*** control 8: ⏶ / ⏷ / ⏴ / ⏵ keys on keypad (balanceless-bumpless switching available) 10: Pattern operation	N	Y	0	
F02	Operation Method	0: FWD/REV/STOP keys on keypad (Motor rotational direction specified by terminal command ***FWD***/***REV***) 1: Terminal command ***FWD*** or ***REV*** 2: FWD/STOP keys on keypad (forward) 3: REV/STOP keys on keypad (reverse)	N	Y	0	
F03	Maximum Frequency 1	25.0 to 120.0 Hz	N	Y	50.0	
F04	Base Frequency 1	25.0 to 120.0 Hz	N	Y	50.0	
F05	Rated Voltage at Base Frequency 1	0: Output a voltage in proportion to input voltage 160 to 500 V: Output an AVR-controlled voltage	N	Y	E: 400 A: 415 C: 380	
F06	Maximum Output Voltage 1	160 to 500 V: Output an AVR-controlled voltage	N	Y		
F07	Acceleration Time 1	0.00 to 3600.00 s Note: Entering 0.00 cancels the acceleration time, requiring external soft-start.	Y	Y	20.00	
F08	Deceleration Time 1		Y	Y	20.00	
F09	Torque Boost 1	0.0% to 20.0% (percentage with respect to "F05: Rated Voltage at Base Frequency 1")	Y	Y	*1	
F10	Electronic Thermal Overload Protection for Motor 1 (Select motor characteristics)	1: For a general-purpose motor with shaft-driven cooling fan 2: For an inverter-driven motor, non-ventilated motor, or motor with separately powered cooling fan	Y	Y	1	
F11	(Overload detection level)	OFF: Disable 1% to 135% of the inverter rated current	Y	Y1	*3	
F12	(Thermal time constant)	0.5 to 75.0 min	Y	Y	*2	
F14	Restart Mode after Momentary Power Failure (Mode selection)	0: Trip immediately 1: Trip after a recovery from power failure 3: Continue to run, for heavy inertia or general loads 4: Restart at the frequency at which the power failure occurred, for general loads 5: Restart at the starting frequency	Y	Y	E: 0 A/C: 1	
F15	Frequency Limiter (High)	0.0 to 120.0 Hz	Y	Y	70.0	
F16	(Low)	0.0 to 120.0 Hz	Y	Y	0.0	
F18	Bias (Frequency command 1)	-100.00% to 100.00%	Y*	Y	0.00	
F20	DC Braking 1 (Braking starting frequency)	0.0 to 60.0 Hz	Y	Y	0.0	
F21	(Braking level)	0% to 60% on the basis of inverter rated current	Y	Y	0	
F22	(Braking time)	OFF (Disable); 0.01 to 30.00 s	Y	Y	OFF	
F23	Starting Frequency 1	0.1 to 60.0 Hz	Y	Y	0.5	
F24	(Holding time)	0.00 to 10.00 s	Y	Y	0.00	
F25	Stop Frequency	0.1 to 60.0 Hz	Y	Y	0.2	
F26	Motor Sound (Carrier frequency)	0.75 to 16 kHz (0.75 to 37 kW)	Y	Y	2	
F27	(Tone)	0: Level 0 (Inactive) 1: Level 1 2: Level 2 3: Level 3	Y	Y	0	
F29	Analog Output [FM1] (Mode selection)	0: Output in voltage (0 to 10 VDC) 1: Output in current (4 to 20 mA DC) 2: Output in current (0 to 20 mA DC)	Y	Y	0	
F30	(Voltage adjustment)	0% to 300%	Y*	Y	100	

Code	Name	Data setting range	Change when running	Data copying	Default setting
F31	Analog Output [FM1] (Function)	Select a function to be monitored from the followings. 0: Output frequency 1 (before slip compensation) 1: Output frequency 2 (after slip compensation) 2: Output current 3: Output voltage 4: Output torque 5: Load factor 6: Input power 7: PID feedback amount 9: DC link bus voltage 10: Universal AO (Note 1) 13: Motor output 14: Calibration (+) (Note 1) 15: PID command (SV) 16: PID output (MV) 18: Heat sink temperature (200°C/10 V) 20: Reference frequency 50: PID feedback amount 1 (PV1) 51: PID command 1 (SV1) 52: PID control 1 deviation (ERR1) (Note 2) 53: PID control final deviation (ERR) (Note 2) 54: PID feedback amount 2 (PV2) 55: PID command 2 (SV2) 56: PID control 2 deviation (ERR2) (Note 2) 60: External PID feedback amount 1 (EPID1-PV) 61: External PID command 1 (EPID1-SV) 62: External PID control 1 deviation (EPID1-ERR) (Note 2) 63: External PID control 2 final deviation (EPID-ERR) (Note 2) 65: External PID final output 1 (EPID1-OUT) 70: External PID feedback amount 2 (EPID2-PV) 71: External PID command 2 (EPID2-SV) 72: External PID control 3 deviation (EPID2-ERR) (Note 2) 75: External PID final output 2 (EPID2-OUT) 80: External PID feedback amount 3 (EPID3-PV) 81: External PID command 3 (EPID3-SV) 82: External PID control 3 deviation (EPID3-ERR) (Note 2) 85: External PID final output 3 (EPID3-OUT) 111: Customizable logic output signal 1 (Note 1) 112: Customizable logic output signal 2 (Note 1) 113: Customizable logic output signal 3 (Note 1) 114: Customizable logic output signal 4 (Note 1) 115: Customizable logic output signal 5 (Note 1) 116: Customizable logic output signal 6 (Note 1) 117: Customizable logic output signal 7 (Note 1) (Note 1) Cannot be selected with U02, U03, etc. (Note 2) Deviation output is supported only by option terminal [Ao] (o09).	Y	Y	0
F32	Pulse Output [FM2] (Mode selection)	0: Voltage (0 to +10 VDC) 1: Current (4 to +20 mA DC) 2: Current (0 to +20 mA DC)	Y	Y	0
F34	(Voltage adjustment)	0 to 300%	Y*	Y	0
F35	(Function)	Same as F31.	Y	Y	0
F37	Load Selection/ Auto Torque Boost/ Auto Energy Saving Operation 1	0: Variable torque load 1: Constant torque load 2: Auto torque boost 3: Auto energy saving (Variable torque load during ACC/DEC) 4: Auto energy saving (Constant torque load during ACC/DEC) 5: Auto energy saving (Auto torque boost during ACC/DEC)	N	Y	1
F40	Torque Limiter 1 (Driving)	OFF: Disable	Y	Y	OFF
F41	(Braking)	20% to 150%: Torque limiter level			
F42	Drive Control Selection 1	0: V/f control with slip compensation inactive 1: Dynamic torque vector control 2: V/f control with slip compensation active	N	Y	0
F43	Current Limiter (Mode selection)	0: Disable (No current limiter works.) 1: Enable at constant speed (Disable during ACC/DEC) 2: Enable during ACC/constant speed operation	Y	Y	2
F44	(Level)	20% to 120% (Assuming the inverter rated current as 100%.)	Y	Y	120

E codes: Extension Terminal Functions

Code	Name	Data setting range	Change when running	Data copying	Default setting
E01	Terminal [X1] Function	Selecting function code data assigns the corresponding function to terminals [X1] to [X7] as listed below. 0 (1000): Select multistep frequency (0 to 1 steps) (***SS1***) 1 (1001): Select multistep frequency (0 to 3 steps) (***SS2***) 2 (1002): Select multistep frequency (0 to 7 steps) (***SS4***) 3 (1003): Select multistep frequency (0 to 15 steps) (***SS8***) 4 (1004): Select ACC/DEC time (2 steps) (***RT1***) 5 (1005): Select ACC/DEC time (4 steps) (***RT2***) 6 (1006): Enable 3-wire operation (***HLD***) 7 (1007): Coast to a stop (***BX***) 8 (1008): Reset alarm (***RST***) 9 (1009): Enable external alarm trip (9 = Active OFF, 1009 = Active ON) (***THR***) 11 (1011): Select frequency command 2/1 (***Hz2/Hz1***) 13: Enable DC braking (***DCBRK***) 14 (1014): Select torque limiter level 2/1 (***TL2/TL1***) 15: Switch to commercial power (50 Hz) (***SW50***) 16: Switch to commercial power (60 Hz) (***SW60***) 17 (1017): UP (Increase output frequency) (***UP***) 18 (1018): DOWN (Decrease output frequency) (***DOWN***) 19 (1019): Enable data change with keypad (***WE-KP***) 20 (1020): Cancel PID control (***Hz/PID***) 21 (1021): Switch normal/inverse operation (***IVS***) 22 (1022): Interlock (***IL***) 24 (1024): Enable communications link via RS-485 or fieldbus (option) (***LE***) 25 (1025): Universal DI (***U-DI***) 26 (1026): Enable auto search for idling motor speed at starting (***STM***) 30 (1030): Force to stop (30 = Active OFF, 1030 = Active ON) (***STOP***) 33 (1033): Reset PID integral and differential components (***PID-RST***) 34 (1034): Hold PID integral component (***PID-HLD***) 35 (1035): Select local (keypad) operation (***LOC***) 38 (1038): Enable run commands (***RE***) 39: Protect motor from dew condensation (***DWP***) 40: Enable integrated sequence to switch to commercial power (50 Hz) (***ISW50***) 41: Enable integrated sequence to switch to commercial power (60 Hz) (***ISW60***) 58 (1058): Reset UP/DOWN frequency (***STZ***) 72 (1072): Count the run time of commercial power-driven motor 1 (***CRUN-M1***) 80 (1080): Cancel customizable logic (***CLC***) 81 (1081): Clear all customizable logic timers (***CLTC***) 87 (1087): Run command 2/1 (***FR2/FR1***) 88: Run forward 2 (***FWD2***) 89: Run reverse 2 (***REV2***) 100: No function assigned (***NONE***) 132 (1132): Filter clogging reverse rotation command (***FRC***) 133 (1133): Switch PID channel (***PID2/1***) 134: Switch to fire mode (***FMS***) 149 (1149): Switch pump control (***PCHG***) 171 (1171): PID multistep command (***PID-SS1***) 172 (1172): PID multistep command (***PID-SS2***) 181 (1181): External PID multistep command (***EPID-SS1***) 182 (1182): External PID multistep command (***EPID-SS2***)	N	Y	0
E02	Terminal [X2] Function		N	Y	1
E03	Terminal [X3] Function		N	Y	6
E04	Terminal [X4] Function		N	Y	7
E05	Terminal [X5] Function		N	Y	8
E06	Terminal [X6] Function		N	Y	11
E07	Terminal [X7] Function		N	Y	35

Code	Name	Data setting range	Change when running	Data copying	Default setting	
		190 (1190): Cancel timer (***TMC***) 191 (1191): Enable timer 1 (***TM1***) 192 (1192): Enable timer 2 (***TM2***) 193 (1193): Enable timer 3 (***TM3***) 194 (1194): Enable timer 4 (***TM4***) 201 (1201): External PID control 1 ON command (***EPID1-ON***) 202 (1202): Cancel external PID control 1 (***%/EPID1***) 203 (1203): Switch normal/inverse operation under external PID control 1 (***EPID1-IVS***) 204 (1204): Reset external PID1 integral and differential components (***EPID1-RST***) 205 (1205): Hold external PID1 integral component(***EPID1-HLD***) 211 (1211): External PID control 2 ON command (***EPID2-ON***) 212 (1212): Cancel external PID control 2 (***%/EPID2***) 213 (1213): Switch normal/inverse operation under external PID control 2 (***EPID2-IVS***) 214 (1214): Reset external PID2 integral and differential components (***EPID2-RST***) 215 (1215): Hold external PID2 integral component(***EPID2-HLD***) 221 (1221): External PID control 3 ON command (***EPID3-ON***) 222 (1222): Cancel external PID control 3 (***%/EPID3***) 223 (1223): Switch normal/inverse operation under external PID control 3 (***EPID3-IVS***) 224 (1224): Reset external PID3 integral and differential components (***EPID3-RST***) 225 (1225): Hold external PID3 integral component(***EPID3-HLD***) Setting the value in parentheses ( ) shown above assigns a negative logic output to a terminal. (True if OFF.) Setting the value of 1000s in parentheses ( ) shown above assigns a negative logic input to a terminal.				
E10	Acceleration Time 2	0.00 to 3600.00 s Note: Entering 0.00 cancels the acceleration time, requiring external soft-start and -stop.	Y	Y	20.00	
E11	Deceleration Time 2		Y	Y	20.00	
E12	Acceleration Time 3		Y	Y	20.00	
E13	Deceleration Time 3		Y	Y	20.00	
E14	Acceleration Time 4		Y	Y	20.00	
E15	Deceleration Time 4		Y	Y	20.00	
E16	Torque Limiter 2(Driving)	OFF: Disable 20% to 150%: Torque limiter level	Y	Y	OFF	
E17	(Braking)		Y	Y	OFF	
E20	Terminal [Y1] Function	Selecting function code data assigns the corresponding function to terminals [Y1] to [Y5A/C] and [30A/B/C] as listed below. 0 (1000): Inverter running (***RUN***) 1 (1001): Frequency (speed) arrival signal (***FAR***) 2 (1002): Frequency (speed) detected (***FDT***) 3 (1003): Undervoltage detected (Inverter stopped) (***LU***) 5 (1005): Inverter output limiting (***IOL***) 6 (1006): Auto-restarting after momentary power failure (***IPF***) 7 (1007): Motor overload early warning (***OL***) 10 (1010): Inverter ready to run (***RDY***) 11: Switch motor drive source between commercial power and inverter output (For MC on commercial line) (***SW88***) 12: Switch motor drive source between commercial power and inverter output (For secondary side) (***SW52-2***) 13: Switch motor drive source between commercial power and inverter output (For primary side) (***SW52-1***) 15 (1015): Select ***AX*** terminal function (For MC on primary side) (***AX***) 16 (1016): Shifted to pattern operation stage (***TU***) 17 (1017): Pattern operation cycle completed (***TO***) 18 (1018): Pattern operation stage number (***STG1***) 19 (1019): Pattern operation stage number (***STG2***) 20 (1020): Pattern operation stage number (***STG4***) 22 (1022): Inverter output limiting with delay (***IOL2***) 25 (1025): Cooling fan in operation (***FAN***) 26 (1026): Auto-resetting (***TRY***) 27 (1027): Universal U-DO (***U-DO***) 28 (1028): Heat sink overheat early warning (***OH***) 30 (1030): Lifetime alarm (***LIFE***) 31 (1031): Frequency (speed) detected 2 (***FDT2***) 33 (1033): Reference loss detected (***REF OFF***) 35 (1035): Inverter output on (***RUN2***) 36 (1036): Overload prevention control (***OLP***) 37 (1037): Current detected (***ID***) 42 (1042): PID alarm (***PID-ALM***) 45 (1045): Under PID control (***PID-CTL***)	N	Y	0	
E21	Terminal [Y2] Function		N	Y	1	
E22	Terminal [Y3] Function		N	Y	2	
E23	Terminal [Y4] Function		N	Y	7	
E24	Terminal [Y5A/C] Function		N	Y	15	
E27	Terminal [30A/B/C] Function (Relay output)		N	Y	99	

Code	Name	Data setting range	Change when running	Data copying	Default setting	
		44 (1044): Motor stopped due to slow flowrate under PID control (***PID-STP***) 45 (1045): Low output torque detected (***U-TL***) 52 (1052): Running forward (***FRUN***) 53 (1053): Running reverse (***RRUN***) 54 (1054): In remote operation (***RMT***) 55 (1055): Run command entered (***AX2***) 56 (1056): Motor overheat detected by thermistor (***THM***) 59 (1059): Terminal [C1] wire break (***C1OFF***) 84 (1084): Maintenance timer (***MNT***) 87(1087): Frequency arrival signal (***FARFDT***) 88(1088): Auxiliary motor drive signal (***AUX_L***) 95(1095): Running in fire mode (***FMRUN***) 98 (1098): Light alarm (***L-ALM***) 99 (1099): Alarm output (for any alarm) (***ALM***) 101(1101): EN terminal detection circuit error (***DECF***) 102(1102): EN terminal OFF (***ENOFF***) 111 (1111): Customizable logic output signal 1 (***CLO1***) 112 (1112): Customizable logic output signal 2 (***CLO2***) 113 (1113): Customizable logic output signal 3 (***CLO3***) 114 (1114): Customizable logic output signal 4 (***CLO4***) 115 (1115): Customizable logic output signal 5 (***CLO5***) 116 (1116): Customizable logic output signal 6 (***CLO6***) 117 (1117): Customizable logic output signal 7 (***CLO7***) 175 (1175): Motor 8 being driven by commercial power (***M8_L***) 190 (1190): In timer operation (***TMD***) 191 (1191): Timer 1 enabled (***TMD1***) 192 (1192): Timer 2 enabled (***TMD2***) 193 (1193): Timer 3 enabled (***TMD3***) 194 (1194): Timer 4 enabled (***TMD4***) 200 (1200): Under PID2 control (***PID2***) 201 (1201): PID1 alarm (***PV1-ALM***) 202 (1202): PID1 feedback error (***PV1-OFF***) 203 (1203): PID2 alarm (***PV2-ALM***) 204 (1204): PID2 feedback error (***PV2-OFF***) 211 (1211): Under external PID1 control (***EPID1-CTL***) 212 (1212): External PID1 output (***EPID1-OUT***) 213 (1213): Running under external PID1 (***EPID1-RUN***) 214 (1214): External PID1 alarm (***EPV1-ALM***) 215 (1215): External PID1 feedback error (***EPV1-OFF***) 221 (1221): Under external PID2 control (***EPID2-CTL***) 222 (1222): External PID2 output (***EPID2-OUT***) 223 (1223): Running under external PID2 (***EPID2-RUN***) 224 (1224): External PID2 alarm (***EPV2-ALM***) 225 (1225): External PID2 feedback error (***EPV2-OFF***) 231 (1231): Under external PID3 control (***EPID3-CTL***) 232 (1232): External PID3 output (***EPID3-OUT***) 233 (1233): Running under external PID3 (***EPID3-RUN***) 234 (1234): External PID3 alarm (***EPV3-ALM***) 235 (1235): External PID3 feedback error (***EPV3-OFF***) Setting the value in parentheses ( ) shown above assigns a negative logic output to a terminal. (True if OFF.) Setting the value of 1000s in parentheses ( ) shown above assigns a negative logic input to a terminal.				

Code	Name	Data setting range	Change when running	Data copying	Default setting	
E30	Frequency Arrival (Hysteresis width)	0.0 to 10.0 Hz	Y	Y	2.5	
E31	Frequency Detection 1 (Level)	0.0 to 120.0 Hz	Y	Y	50.0	
E32	(Hysteresis width)	0.0 to 120.0 Hz	Y	Y	1.0	
E34	Overload Early Warning/Current Detection (Level)	OFF: Disable 1 to 150% of inverter rated current	Y	Y1	*3	
E35	(Timer)	0.01 to 600.00s	Y	Y	10.00	
E61	Terminal [12] Extended Function	0: None 1: Auxiliary frequency command 1 (*) 2: Auxiliary frequency command 2 (*) 3: PID process command 1 (*) 4: PID process command 2 (*) 5: PID feedback value 1 (*) 12: Acceleration/deceleration time ratio setting 13: Upper limit frequency 14: Lower limit frequency 20: Analog signal input monitor 30: PID feedback value 2 (*) 31: Auxiliary input 1 to PID process command (*) 32: Auxiliary input 2 to PID process command (*) 33: Flow sensor (*) 41: External PID process command 1 (*) 42: External PID feedback value 1 (*) 43: External PID manual command 1 (*) 44: External PID process command 2 (*) 45: External PID feedback value 2 (*) 46: External PID manual command 2 (*) 47: External PID process command 3 (*) 48: External PID feedback value 3 (*) 49: External PID manual command 3 (*) (*) Available for customizable logic	N	Y	0	
E62	Terminal [C1] Extended Function		N	Y	0	
E63	Terminal [V2] Extended Function		N	Y	0	
E64	Saving of Digital Reference Frequency	0: Automatic saving (when main power is turned OFF) 1: Saving by pressing (SET) key	Y	Y	1	
E65	Reference Loss Detection (Continuous running frequency)	OFF: Cancel Decel: Decelerate to stop 20% to 120%	Y	Y	OFF	
E80	Low Torque Detection (Level)	0% to 150%	Y	Y	20	
E81	(Timer)	0.01 to 600.00 s	Y	Y	20.00	
E82	Switching Frequency of Accel/Decel Time in Low-Speed Domain	Inherit: Follow the setting of F16 0.1 to 120.0 Hz	Y	Y	Inherit	
E83	Acceleration Time in Low-Speed Domain	Inherit: Follow the current acceleration time 0.01 to 3600.00 s: Acceleration time from 0 Hz to E82	Y	Y	Inherit	
E84	Deceleration Time in Low-Speed Domain	Inherit: Follow the current deceleration time 0.01 to 3600.00 s: Deceleration time from E82 to 0 Hz	Y	Y	Inherit	
E85	Gradual Deceleration Time Switching Frequency	OFF: Disable 0.1 to 120.0 Hz	Y	Y	OFF	
E86	Gradual Deceleration Time (Check valve protection)	Inherit: Follow the current deceleration time 0.01 to 3600.00 s: Deceleration time from E82 to E85	Y	Y	Inherit	
E98	Terminal [FWD] Function	Selecting function code data assigns the corresponding function to terminals [FWD] and [REV] as listed below. 98: Run forward (***FWD***) 99: Run reverse (***REV***) Same functions described on parameters E01~E07 are also available. Setting the value in parentheses ( ) shown above assigns a negative logic output to a terminal. (True if OFF.) Setting the value of 1000s in parentheses ( ) shown above assigns a negative logic input to a terminal.	N	Y	98	
E99	Terminal [REV] Function		N	Y	99	

C codes: Control Functions of Frequency

Code	Name	Data setting range	Change when running	Data copying	Default setting
C01	Jump Frequency 1	0.0 to 120.0 Hz	Y	Y	0.0
C02	2		Y	Y	0.0
C03	3		Y	Y	0.0
C04	(Hysteresis width)	0.0 to 30.0 Hz	Y	Y	3.0
C05	Multistep Frequency 1	0.00 to 120.00 Hz	Y	Y	0.00
C06	2		Y	Y	0.00
C07	3		Y	Y	0.00
C08	4		Y	Y	0.00
C09	5		Y	Y	0.00
C10	6		Y	Y	0.00
C11	7		Y	Y	0.00
C12	8		Y	Y	0.00
C13	9		Y	Y	0.00
C14	10		Y	Y	0.00
C15	11		Y	Y	0.00
C16	12		Y	Y	0.00
C17	13		Y	Y	0.00
C18	14		Y	Y	0.00
C19	15		Y	Y	0.00
C21	Pattern Operation (Mode selection)	0: Carry out a single cycle of the specified pattern operation and stop the inverter output 1: Carry out the specified pattern operation repeatedly and stop the inverter output upon receipt of a stop command. 2: Carry out a single cycle of the specified pattern operation and continue to run at the last reference frequency.	N	Y	0
C22	Pattern Operation (Stage 1)	0.00 to 6000.00 s FWD/RED 1 to 4	Y	Y	0.00 FWD 1
C23	(Stage 2)				
C24	(Stage 3)				
C25	(Stage 4)				
C26	(Stage 5)				
C27	(Stage 6)				
C28	(Stage 7)				
C30	Frequency Command 2	0: Enable ⌃ / ⌄ keys on the keypad 1: Voltage input to terminal [12] (-10 to +10 VDC) 2: Current input to terminal [C1] (4 to 20 mA DC) 3: Sum of voltage and current inputs to terminals [12] and [C1] 5: Voltage input to terminal [V2] (0 to 10 VDC) 7: Terminal command ***UP***/***DOWN*** control 8: Enable ⌃ / ⌄ keys on the keypad (balanceless-bumpless switching available) 10: Pattern operation	N	Y	2
C31	Analog Input Adjustment for [12] (Offset)	-5.0% to 5.0%	Y*	Y	0.0
C32	(Gain)	0.00% to 200.00%	Y*	Y	100.00
C33	(Filter time constant)	0.00 to 5.00 s	Y	Y	0.05
C34	(Gain base point)	0.00% to 100.00%	Y*	Y	100.00
C35	(Polarity)	0: Bipolar 1: Unipolar	N	Y	1
C36	Analog Input Adjustment for [C1] (Offset)	-5.0% to 5.0%	Y*	Y	0.0
C37	(Gain)	0.00% to 200.00%	Y*	Y	100.00
C38	(Filter time constant)	0.00 to 5.00s	Y	Y	0.05
C39	(Gain base point)	0.00% to 100.00%	Y*	Y	100.00
C40	Terminal [C1] Input Range Selection	0: 4 to 20 mA 1: 0 to 20 mA	N	Y	0
C41	Analog Input Adjustment for [V2] (Offset)	-5.0% to 5.0%	Y*	Y	0.0
C42	(Gain)	0.00% to 200.00%	Y*	Y	100.00
C43	(Filter time constant)	0.00 to 5.00 s	Y	Y	0.05
C44	(Gain base point)	0.00% to 100.00%	Y*	Y	100.00
C45	(Polarity)	0: Bipolar 1: Unipolar	N	Y	1
C53	Selection of Normal/Inverse Operation (Frequency command 1)	0: Normal operation 1: Inverse operation	Y	Y	0
C55	Analog Input Adjustment for Terminal [12] (Bias value)	-100.00 to 100.00%	Y	Y	0.00
C56	(Bias base point)	0.00 to 100.00%	Y	Y	0.00

Code	Name	Data setting range	Change when running	Data copying	Default setting	
C58	Analog Input Adjustment for Terminal [12] (Display unit)	1: none 2: % 4: r/min 7: kW Flowrate 20: m^3/s 21: m^3/min 22: m^3/h 23: L/s 24: L/min 25: L/h Pressure 40: Pa 41: kPa 42: MPa 43: mbar 44: bar 45: mmHg 46: psi (Pound per square inch) 47: mWG 48: inWG Temperature 60: K 61: °C 62: °F Density 80: ppm	Y	Y	2	
C59	(Maximum scale)	-999.00 to 0.00 to 9990.00	N	Y	100	
C60	(Minimum scale)	-999.00 to 0.00 to 9990.00	N	Y	0.00	
C61	Analog Input Adjustment for Terminal [C1] (Bias value)	-100.00 to 100.00%	Y	Y	0.00	
C62	(Bias base point)	0.00 to 100.00%	Y	Y	0.00	
C64	(Display unit)	Same as C58.	Y	Y	2	
C65	(Maximum scale)	-999.00 to 0.00 to 9990.00	N	Y	100	
C66	(Minimum scale)	-999.00 to 0.00 to 9990.00	N	Y	0.00	
C67	Analog Input Adjustment for Terminal [V2] (Bias value)	-100.00 to 100.00%	Y	Y	0.00	
C68	(Bias base point)	0.00 to 100.00%	Y	Y	0.00	
C70	(Display unit)	Same as C58.	Y	Y	2	
C71	(Maximum scale)	-999.00 to 0.00 to 9990.00	N	Y	100	
C72	(Minimum scale)	-999.00 to 0.00 to 9990.00	N	Y	0.00	

P codes: Motor 1 Parameters

Code	Name	Data setting range	Change when running	Data copying	Default setting	
P01	Motor 1 (No. of poles)	2 to 22 poles	N	Y1	4	
P02	(Rated capacity)	0.01 to 1000.00 kW (when P99 = 0 or 4) 0.01 to 1000.00 HP (when P99 = 1)	N	Y1	*6	
P03	(Rated current)	0.00 to 2000.00 A	N	Y1	*6	
P04	(Auto-tuning)	0: Disable 1: Tune the motor while it is stopped (%R1, %X) 2: Tune the motor while it is rotating under V/f control (%R1, %X, no-load current)	N	N	0	
P05	(Online-tuning)	0: Disable 1: Enable	Y	Y	0	
P06	(No-load current)	0.00 to 2000.00 A	N	Y1	*6	
P07	(%R1)	0.00% to 50.00%	Y	Y1	*6	
P08	(%X)	0.00% to 50.00%	Y	Y1	*6	
P10	(Slip compensation response time)	0.01 to 10.00 s	Y	Y1	0.50	
P12	(Rated slip frequency)	0.00 to 15.00 Hz	N	Y1	*6	
P99	Motor 1 Selection	0: Motor characteristics 0 (Fuji standard motors, 8-series) 1: Motor characteristics 1 (HP rating motors) 4: Other motors	N	Y1	0	

H codes: High Performance Functions

Code	Name	Data setting range	Change when running	Data copying	Default setting	
H03	Data Initialization	0: Disable initialization 1: Initialize all function code data to factory defaults 2: Initialize motor 1 parameters 10: Initialize real-time clock information 11: Initialize function code data except communication function codes 12: Initialize U code data (customizable logic function codes) 71: Default setting for compressors 72: Default setting for fans 73: Default setting for single pump	N	N	0	
H04	Auto-reset (Times)	OFF: Disable; 1 to 20	Y	Y	OFF	
H05	(Reset interval)	0.5 to 60.0 s	Y	Y	5.0	
H06	Cooling Fan ON/OFF Control	0: Disable (Always in operation) 1: Enable (ON/OFF controllable)	Y	Y	1	
H07	Acceleration/Deceleration Pattern	0: Linear 1: S-curve (Weak) 2: S-curve (Strong) 3: Curvilinear	Y	Y	0	
H08	Rotational Direction Limitation	0: Disable 1: Enable (Reverse rotation inhibited) 2: Enable (Forward rotation inhibited) 3: Enable (Reverse rotation inhibited, setting only) 4: Enable (Forward rotation inhibited, setting only)	N	Y	0	
H09	Starting Mode (Auto search)	0: Disable 1: Enable (At restart after momentary power failure) 2: Enable (At restart after momentary power failure and at normal start)	N	Y	0	
H11	Deceleration Mode	0: Normal deceleration 1: Coast-to-stop	Y	Y	0	
H12	Instantaneous Overcurrent Limiting (Mode selection)	0: Disable 1: Enable	Y	Y	1	
H13	Restart Mode after Momentary Power Failure (Restart time)	0.1 to 20.0 s	Y	Y1	*2	
H14	(Frequency fall rate)	Inherit: With the selected deceleration time 0.01 to 100.00 Hz/s Auto: With the current limiter	Y	Y	Auto	
H15	(Continuous running level)	400 to 600 V	Y	Y1	470	
H16	(Allowable momentary power failure time)	0.0 to 30.0 s Auto: Automatically determined by inverter	Y	Y	Auto	
H26	Thermistor (for motor) (Mode selection)	0: Disable 1: PTC (The inverter immediately trips with OH4 displayed.) 2: PTC (The inverter issues output signal ***THM*** and continues to run.)	Y	Y	0	
H27	(Level)	0.00 to 5.00 V	Y	Y	0.35	
H30	Communications Link Function (Mode selection)	Frequency command / Run command 0: F01/C30 / F02 1: RS-485 (Port 1) / F02 2: F01/C30 / RS-485 (Port 1) 3: RS-485 (Port 1) / RS-485 (Port 1) 4: RS-485 (Port 2) / F02 5: RS-485 (Port 2) / RS-485 (Port 1) 6: F01/C30 / RS-485 (Port 2) 7: RS-485 (Port 1) / RS-485 (Port 2) 8: RS-485 (Port 2) / RS-485 (Port 2)	Y	Y	0	
H42	Capacitance of DC Link Bus Capacitor	Meas (Measure initial value), Failed (Measurement failed), 2 to 65535 Indication for replacement of DC link bus capacitor	Y	N	-	
H43	Cumulative Run Time of Cooling Fan	Indication for replacement of cooling fan 0 to 99990 (in units of 10 hours)	Y	N	-	
H44	Startup Counter for Motor 1	Indication of cumulative startup count 0 to 65535	Y	N	-	
H45	Mock Alarm	0: Disable 1: Enable (Once a mock alarm occurs, the data automatically returns to 0.)	Y	N	0	
H46	Starting Mode (Auto search delay time 2)	0.1 to 20.0 s	Y	Y1	*6	
H47	Initial Capacitance of DC Link Bus Capacitor	Meas (Measure initial value), Failed (Measurement failed), 2 to 65535 Indication for replacement of DC link bus capacitor	Y	N	-	
H48	Cumulative Run Time of Capacitors on Printed Circuit Boards	Indication for replacement of capacitors 0 to 99990 (in units of 10 hours)	Y	N	-	
H49	Starting Mode (Auto search delay time 1)	0.0 to 10.0 s	Y	Y	0.0	

Code	Name	Data setting range	Change when running	Data copying	Default setting
H50	Non-linear V/f Pattern 1 (Frequency)	OFF: Cancel, 0.1 to 120.0 Hz	N	Y	*7
H51	(Voltage)	0 to 500: Output an AVR-controlled voltage	N	Y1	E/A: *8 C: 0
H52	Non-linear V/f Pattern 2 (Frequency)	OFF: Cancel, 0.1 to 120.0 Hz	N	Y	OFF
H53	(Voltage)	0 to 500: Output an AVR-controlled voltage	N	Y1	0
H56	Deceleration Time for Forced Stop	0.00 to 3600 s	Y	Y	20.0
H61	Multistep Frequency + UP/DOWN Control (Initial frequency setting)	1: Last UP/DOWN command value on releasing the run command 13 to 106: Multistep frequency + UP/DOWN command (Initial value to be preserved)	N	Y	1
H63	Low Limiter (Mode selection)	0: Limit by F16 (Frequency limiter: Low) and continue to run 1: If the output frequency lowers below the one limited by F16 (Frequency limiter: Low), decelerate to stop the motor.	Y	Y	0
H64	(Lower limiting frequency)	Inherit: Depends on F16 (Frequency limiter, Low) 0.1 to 60.0 Hz	Y	Y	2.0
H68	Slip Compensation 1 (Operating conditions)	0: Enable during ACC/DEC and at base frequency or above 1: Disable during ACC/DEC and enable at base frequency or above 2: Enable during ACC/DEC and disable at base frequency or above 3: Disable during ACC/DEC and at base frequency or above	N	Y	0
H69	Automatic Deceleration (Mode selection)	0: Disable 2: Torque limit control with Force-to-stop if actual deceleration time exceeds three times the specified one 3: DC link bus voltage control with Force-to-stop if actual deceleration time exceeds three times the specified one 4: Torque limit control with Force-to-stop disabled 5: DC link bus voltage control with Force-to-stop disabled	Y	Y	0
H70	Overload Prevention Control	OFF: Cancel Inherit: Follow the selected deceleration time 0.01 to 100.00 Hz/s	Y	Y	OFF
H71	Deceleration Characteristics	0: Disable 1: Enable	Y	Y	0
H72	Main Power Down Detection (Mode selection)	0: Disable 1: Enable	Y	Y	1
H76	Torque Limiter for Braking (Frequency increment limit)	0.0 to 120.0 Hz	Y	Y	5.0
H77	Service Life of DC Link Bus Capacitor (Remaining time)	0 to 43800 (in units of 10 hours)	Y	N	-
H78	Maintenance Interval (M1)	OFF: Disable 10 to 99990 (in units of 10 hours)	Y	N	43800
H79	Preset Startup Count for Maintenance (M1)	OFF: Disable 1 to 65535	Y	N	OFF
H80	Output Current Fluctuation Damping Gain for Motor 1	0.00 to 1.00	Y	Y	0.20
H89	Reserved *9	0, 1	Y	Y	1
H90	Reserved *9	0, 1	Y	Y	0
H91	Current Input Wire Break Detection	OFF: Disable, 0.1 to 60.0 s	Y	Y	OFF
H92	Continuity of Running (P)	0.000 to 10.000 times Auto	Y	Y1	Auto
H93	(I)	0.010 to 10.000 s Auto	Y	Y1	Auto
H94	Cumulative Motor Run Time 1	0 to 99990 (The cumulative run time can be modified or reset in units of 10 hours.)	N	N	-
H95	DC Braking (Braking response mode)	0: Slow 1: Quick	Y	Y	1
H96	STOP Key Priority/Start Check Function	Data: 0: STOP key priority: Disable, Start check function: Disable 1: Enable, Disable 2: Disable, Enable 3: Enable, Enable	Y	Y	0
H97	Clear Alarm Data	0: Disable 1: Enable (Setting "1" clears alarm data and then returns to "0.")	Y	N	0
H98	Protection/Maintenance Function (Mode selection)	0 to 255 Bit 0: Lower the carrier frequency automatically (0: Disabled; 1: Enabled) Bit 1: Detect input phase loss (0: Disabled; 1: Enabled) Bit 2: Detect output phase loss (0: Disabled; 1: Enabled) Bit 3: Select life judgment threshold of DC link bus capacitor (0: Factory default level; 1: User setup level) Bit 4: Judge the life of DC link bus capacitor (0: Disabled; 1: Enabled) Bit 5: DC fan lock detection (0: Disabled; 1: Enabled) Bit 7: Switch IP21/IP55 enclosure (0: IP21; 1: IP55)	Y	Y	AQ1M (IP21) 19 AQ1L (IP55) 147

Code	Name	Data setting range	Change when running	Data copying	Default setting	
H104	Number-of-retry Clear Time	0.5 to 5.0 (min)	Y	Y	5.0	
H105	Retry Target Selection	0 to 255 Bit 0: OC1 to OC3 Bit 1: OV1 to OV3 Bit 2: OH1 OH3 OLU Bit 3: - Bit 4: OL1 Bit 5: OH4 Bit 6: - Bit 7: -	Y	Y	225	
H106	Retry Target Selection 2	0 to 255 Bit 0: OH2 Bit 1: LV Bit 2: - Bit 3: - Bit 4: - Bit 5: - Bit 6: - Bit 7: -	Y	Y	0	
H110	Input Phase Loss Protection Avoidance Operation (Mode selection)	0: Disable 1: Enable (Decrease output frequency)	Y	Y	0	
H112	Voltage Shortage Avoidance Operation (Mode selection)	0: Disable 1: Enable (Decrease output frequency)	Y	Y	0	
H114	Automatic Deceleration (Operation level)	0.0 to 50.0% Auto	Y	Y	Auto	
H116	Fire Mode (Mode selection)	0: FMS: ON 1: FMS toggle method 2: FMS latch method	N	Y	0	
H117	(Confirmation time)	0.5 to 10.0 s * Set ON/OFF setting time for FMS signals.	Y	Y	3.0	
H118	(Reference frequency)	Inherit: Follow the ordinary reference frequency specified with F01, etc. 0.1 to 120.0 Hz	Y	Y	Inherit	
H119	(Rotation direction)	0: Follow the run command specified with F02, etc. 2: Forward rotation 3: Reverse rotation	N	Y	0	
H120	(Start method)	0: Follows the start methods specified with instant power failure restart 1: Auto search	Y	Y	0	
H121	(Reset interval)	0.5 to 20.0 s	Y	Y	5.0	
H181	Light Alarm Selection 1	0 to 255 Bit 0: - Bit 1: OH2 Bit 2: OH3 Bit 3: - Bit 4: - Bit 5: OL1 Bit 6: - Bit 7: -	Y	Y	0	
H182	Light Alarm Selection 2	0 to 255 Bit 0: - Bit 1: - Bit 2: Er4 Bit 3: Er5 Bit 4: Er8 Bit 5: ErP Bit 6: - Bit 7: -	Y	Y	0	
H183	Light Alarm Selection 3	0 to 255 Bit 0: - Bit 1: - Bit 2: - Bit 3: CoF, PV1, PV2, PVA, PVb, PVC Bit 4: FAL Bit 5: OL Bit 6: OH Bit 7: LiF	Y	Y	0	

Code	Name	Data setting range	Change when running	Data copying	Default setting	
H184	Light Alarm Selection 4	0 to 255 Bit 0: rEF Bit 1: PA1, PA2, PAA, PAb, PAC Bit 2: UTL Bit 3: PTC Bit 4: rTE Bit 5: Cnt Bit 6: - Bit 7: Lob, dtL	Y	Y	128	
H197	User Password 1 (Mode selection)	0: Disclose all function codes but prohibit any change 1: Disclose function codes selected for quick setup only and allow changing * This specifies the protection of user password 1.	Y	Y	0	

J codes: Application Functions 1

Code	Name	Data setting range	Change when running	Data copying	Default setting	
J21	Dew Condensation Prevention (Duty)	1% to 50%	Y	Y	1	
J22	Commercial Power Switching Sequence	0: Keep inverter operation (Stop due to alarm) 1: Automatically switch to commercial-power operation	N	Y	0	

J1 codes: PID Control 1

Code	Name	Data setting range	Change when running	Data copying	Default setting	
J101	PID Control 1 (Mode selection)	0: Disable 1: Enable (Process control, normal operation) 2: Enable (Process control, inverse operation)	N	Y	0	
J102	(Command selection)	0: Keypad (▲/▼ key) 1: PID command 1 (Analog input: Terminals [12], [C1] and [V2]) 3: ***UP***/***DOWN*** 4: Command via communications link (Use function code S13)	N	Y	0	
J103	(Feedback selection)	1: PID control 1 feedback value 10: Addition (PID control 1 feedback value + PID control 2 feedback value) 11: Difference (PID control 1 feedback value - PID control 2 feedback value) 12: Average (PID control 1 feedback value, PID control 2 feedback value) 13: Maximum (PID control 1 feedback value, PID control 2 feedback value) 14: Minimum (PID control 1 feedback value, PID control 2 feedback value)	N	Y	1	
J104	(Deviation selection)	0: (J102)-(J103) 1: Selection of maximum (selection of maximum for PID control 1 and 2 deviation) 2: Selection of minimum (selection of minimum for PID control 1 and 2 deviation)	N	Y	0	

Code	Name	Data setting range	Change when running	Data copying	Default setting	
J105	PID Control 1 (Display unit)	0: Based on the unit/scale of the PID control 1 feedback amount 1: none 2: % 4: r/min 7: kW Flowrate 20: m^3/s 21: m^3/min 22: m^3/h 23: L/s 24: L/min 25: L/h Pressure 40: Pa 41: kPa 42: MPa 43: mbar 44: bar 45: mmHg 46: psi (Pound per square inch) 47: mWG 48: inWG Temperature 60: K 61: °C 62: °F Density 80: ppm	N	Y	0	
J106	(Maximum scale)	-999.00 to 0.00 to 9990.00	N	Y	100	
J107	(Minimum scale)	-999.00 to 0.00 to 9990.00	N	Y	0.00	
J110	P (Gain)	0.000 to 30.000 times	Y	Y	0.100	
J111	I (Integral time)	0.0 to 3600.0 s	Y	Y	0.0	
J112	D (Differential time)	0.00 to 600.00 s	Y	Y	0.00	
J113	(Feedback filter)	0.0 to 900.0 s	Y	Y	0.5	
J114	(Anti-reset wind-up)	OFF: Disable 0.01 to 9990.00 *10	Y	Y	OFF	
J118	(Upper limit of PID process output)	0.0 to 120.0 Hz; Inherit (Depends on setting of F15)	Y	Y	Inherit	
J119	(Lower limit of PID process output)	0.0 to 120.0 Hz; Inherit (Depends on setting of F16)	Y	Y	Inherit	
J121	(Alarm output selection)	0: Absolute-value alarm 1: Absolute-value alarm (with Hold) 2: Absolute-value alarm (with Latch) 3: Absolute-value alarm (with Hold and Latch) 4: Deviation alarm 5: Deviation alarm (with Hold) 6: Deviation alarm (with Latch) 7: Deviation alarm (with Hold and Latch)	Y	Y	0	
J122	(Upper level alarm (AH))	-999.00 to 0.00 to 9990.00 *10 OFF	Y	Y	OFF	
J124	(Lower level alarm (AL))	-999.00 to 0.00 to 9990.00 *10 OFF	Y	Y	OFF	
J127	(Feedback failure detection (Mode selection))	0: Disable (Turns ON output signals (PV1-OFF) and continues operation.) 1: Enable (Free run stop (PV1 trip)) 2: Enable (Deceleration and stop (PV1 trip)) 3: Enable (Continuation of operation at the maximum frequency (upper limit frequency)) 4: Enable (Continuation of operation at the minimum frequency (lower limit frequency)) 5: Enable (Continuation of operation at the frequency used when failure is detected.) 6: Enable (Shift to PID control 2 (PID control 1 is restored when failure is recovered from.))	Y	Y	0	

Code	Name	Data setting range	Change when running	Data copying	Default setting	
J128	(Feedback failure continuation duration)	0 to 3600 s; Cont. Cont. (Mode selection: continuation of operation specified with J127. PV1 trip after stop (output shutoff).)	Y	Y	Cont.	
J129	(Feedback failure upper-limit)	-999.00 to 0.00 to 9990.00 *10 Auto: 105% equivalent	Y	Y	Auto	
J130	(Feedback failure lower-limit)	-999.00 to 0.00 to 9990.00 *10 Auto: -5% equivalent	Y	Y	Auto	
J131	(Feedback failure detection time)	0.0 to 300.0 s	Y	Y	0.1	
J136	PID Multistep Command (Multistep command 1)	-999.00 to 0.00 to 9990.00	Y	Y	0.00	
J137	(Multistep command 2)		Y	Y	0.00	
J138	(Multistep command 3)		Y	Y	0.00	
J188	Filter Clogging Prevention/ Anti Jam Function (Input selection)	0: Disable 1: Enable (Anti jam protection, inverter stop with rLo trip) 2: Enable (Filter clogging trouble, inverter stop with FoL trip) 3: Enable (While warning (filter clogging trouble) is output, operation is continued.)	Y	Y	0	
J189	Filter Clogging Prevention Function (Reverse operation cycle time)	OFF: Disable 1 to 10000 h	Y	Y	720	
J190	(Load resistance current)	OFF: Disable 1% to 150% of the inverter rated current	Y	Y	OFF	
J191	(Load resistance PV signal)	-999.00 to 0.00 to 9990.00 *10 OFF	Y	Y	OFF	
J192	(Load resistance detection timer)	0 to 600 s	Y	Y	0	
J193	Filter Clogging Prevention/ Anti Jam Function (Reverse rotation running frequency)	0.0 to 120.0 Hz	Y	Y	5.0	
J194	(Reverse rotation running time)	0 to 600 s	Y	Y	30	
J195	(Number of allowable reverse runs)	1 to 10 times	Y	Y	3	
J198	Wet-bulb temperature presumption control	OFF: Disable 0.01 to 120.00 Hz/min	Y	Y	OFF	

K codes: Keypad Functions

Code	Name	Data setting range	Change when running	Data copying	Default setting	
K01	LCD Monitor (Language selection)	0: Japanese 1: English 2: German 3: French 4: Spanish 5: Italian 6: Chinese 8: Russian (Available soon) 9: Greek (Available soon) 10: Turkish (Available soon) 11: Polish 12: Czech 13: Swedish 14: Portuguese (Available soon) 15: Dutch (Available soon) 16: Malay 17: Vietnamese (Available soon) 18: Thai (Available soon) 19: Indonesian (Available soon) 100: User-customized language (Available soon)	Y	Y	E/A:1 C:6	
K02	Backlight OFF Time	OFF: Always OFF 1 to 30 min.: Automatic OFF time	Y	Y	5	
K03	LCD Monitor (Backlight brightness control)	0 (Dark) to 10 (Light)	Y	Y	5	
K04	(Contrast control)	0 (Light) to 10 (Dark)	Y	Y	5	
K08	LCD Monitor Status Display/Hide Selection	0: Hide 1: Display	Y	Y	1	

Code	Name	Data setting range	Change when running	Data copying	Default setting	
K10	Main Monitor (Display item selection)	0: Speed monitor (select by K11) 13: Output current 14: Output voltage 18: Calculated torque 19: Input power 25: Load factor 26: Motor output 27: Analog input monitor in physical quantity 35: Input watt-hour (The unit depends on K31.) 50: PID command (final) in physical quantity 51: PID feedback amount (final) in physical quantity 52: PID output 53: PID control 1 command in physical quantity 54: PID control 1 feedback amount in physical quantity 55: PID control 2 command in physical quantity 56: PID control 2 feedback amount in physical quantity	Y	Y	0	
K11	Main Monitor (Speed monitor item)	1: Output frequency 1 (before slip compensation) 2: Output frequency 2 (after slip compensation) 3: Reference frequency 4: Motor speed in r/min 5: Load shaft speed in r/min 8: Display speed in %	Y	Y	1	
K12	Main Monitor (Display when stopped)	0: Reference value 1: Output value	Y	Y	0	
K15	Sub Monitor (Display type)	0: Numeric values 1: Bar charts	Y	Y	0	
K16	Sub Monitor 1 (Display item selection)	*Refer to K10 (= 13 to 83) and K11 (= 1 to 8).	Y	Y	13	
K17	Sub Monitor 2 (Display item selection)		Y	Y	19	
K20	Bar Chart 1 (Display item selection)	1: Output frequency 1(before slip compensation) 13: Output current 14: Output voltage 18: Calculated torque 19: Input power 25: Load factor 26: Motor output	Y	Y	1	
K21	Bar Chart 2 (Display item selection)		Y	Y	13	
K22	Bar Chart 3 (Display item selection)		Y	Y	19	
K29	Display Filter	0.0 to 5.0 s	Y	Y	0.5	
K30	Coefficient for Speed Indication	0.01 to 200.00	Y	Y	30.00	
K31	Display Unit for Input Watt-hour Data	0: kWh 1: MWh	Y	Y	0	
K32	Display Coefficient for Input Watt-hour Data	OFF: Cancel or reset 0.001 to 9999.000	Y	Y	0.010	
K33	Long-term, Input Watt-hour Data Monitor	OFF: Cancel or reset 1: Hourly 2: Daily 3: Weekly 4: Monthly	Y	Y	4	
K81	Date Format	0: Y/M/D (year/month/day) 1: D/M/Y (day/month/year) 2: M/D/Y (month/day/year) 3: MD, Y (Month day, year)	Y	Y	E/A: 1 C: 0	
K82	Time Format	0: 24-hour format (Time : Minute : Second) 1: 12-hour format (Time : Minute : Second AM/PM) 2: 12-hour format (AM/PM Time : Minute : Second)	Y	Y	0	
K83	Daylight Saving Time (Summer time)	0: Disable 1: Enable (+ 1 hour) 2: Enable (+ 30 minutes)	Y	Y	0	
K84	(Start date)	Possible to specify in the special menu.	Y	Y	0800H	
K85	(End date)		Y	Y	0800H	
K91	Shortcut Key Function for ‹ in Running Mode (Selection screen)	0: OFF (Disable) 11 to 99	Y	Y	OFF	
K92	Shortcut Key Function for › in Running Mode (Selection screen)	0: OFF (Disable) 11 to 99	Y	Y	64	

Chapter 5
Names and functions of keypad components

The keypad allows you to run and stop the motor, monitor the running status, specify the function code data, and monitor I/O signal states, maintenance information, and alarm information.

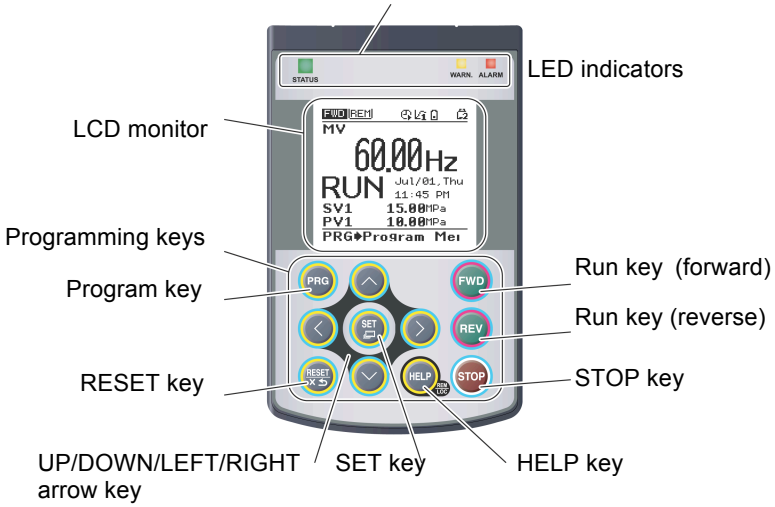

Figure 8.1: Names and Functions of Keypad Components

Table 8.1: Indication of LED Indicators

LED Indicators	Indication	
STATUS (Green)	Shows the inverter running state.	
	Flashing	No run command input (Inverter stopped)
	ON	Run command input
WARN. (Yellow)	Shows the light alarm state.	
	OFF	No light alarm has occurred.
	Flashing /ON	A light alarm has occurred.
ALARM (Red)	Shows the alarm state (heavy alarm).	
	OFF	No heavy alarm has occurred.
	Flashing	A heavy alarm has occurred.

Table 8.2: Overview of Keypad Functions

Number	Key	Function
3-1	PRG	This key switches the operation modes between Running mode/Alarm mode and Programming mode.
3-2	RESET	Reset key which works as follow according to operation modes: ■ In Running mode: This key cancels the screen transaction ■ In Programming mode: This key reset alarm states and switches to Programming mode ■ In Alarm mode: This key cancels the setting done or screen transition
3-3	/	UP/DOWN key which works as follows according to the operation modes: ■ In Running mode: These keys switch to the digital reference frequency and PID command modification screen (when commands from the keypad are enabled). ■ In Programming mode: These keys display multiple alarms and alarm history. ■ In Alarm mode: These keys select menu items, change data and scroll the screen.
	/	These keys move the cursor to the digit of data to be modified, shift the setting item, and switch the screen.
3-4	SET	Set key which works as follows according to the operation modes: ■ In Running mode: This key switch to the selection screen of the LCD content. ■ In Programming mode: Pressing this key switch to the alarm information screen. ■ In Alarm mode: Pressing this key establishes the selected items and data changed
3-5	HELP	Pressing this key call up the HELP screen according to the current display state. Holding it down for 2 seconds toggles between the remote and local modes.
3-6	FWD	Pressing this key starts running the motor in the forward rotation (when a run command from the keypad is enabled).

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